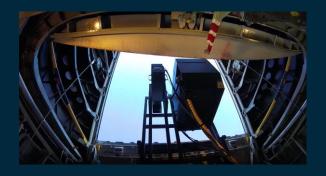


## 2016 AERIAL EXPEDITION

Observations of marine debris in the North Pacific subtropical gyre using RGB and SWIR cameras as well as LIDAR.

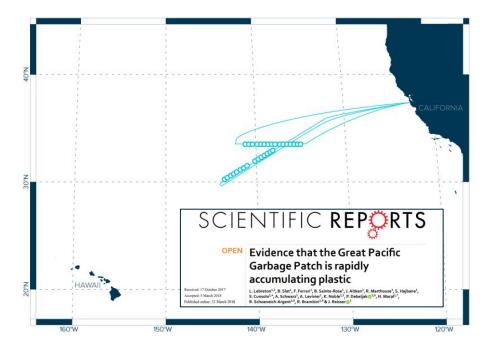




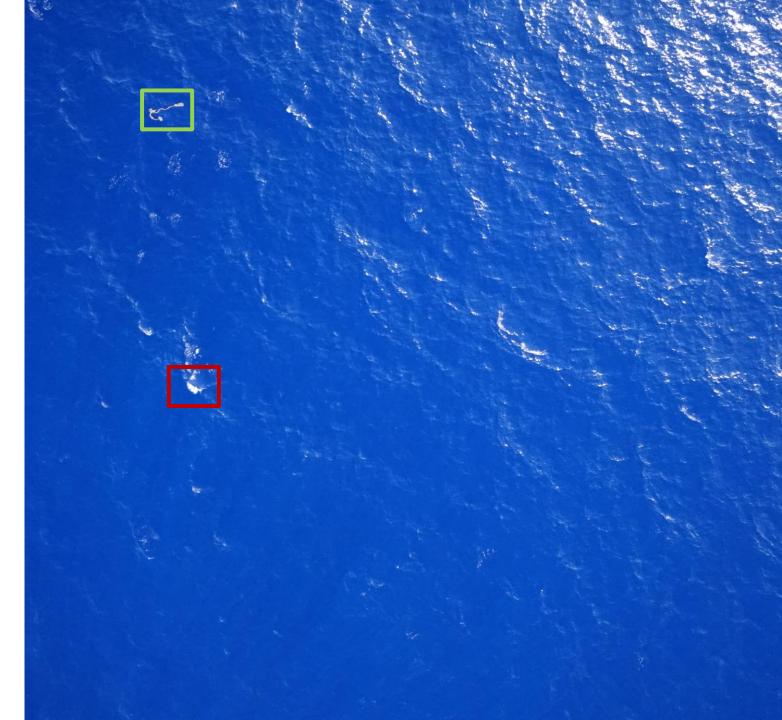


## MARINE DEBRIS DETECTION

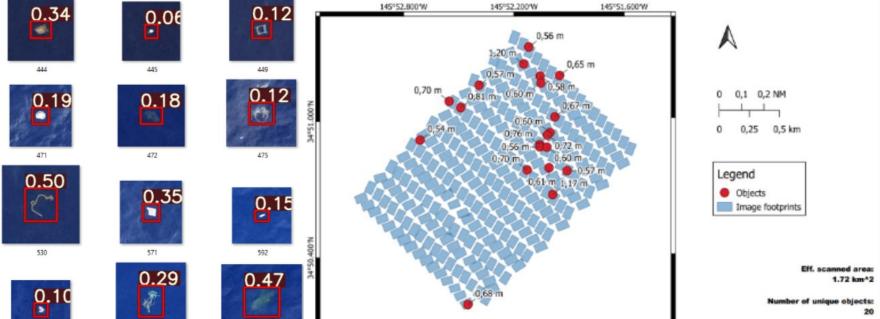
N = 7,298 aerial images of the sea surface were recorded during two reconnaissance flights above the accumulation zone.



Tagging of debris was initially performed by observers. Labelled imagery was then used to train an image reconnaissance algorithm.







674

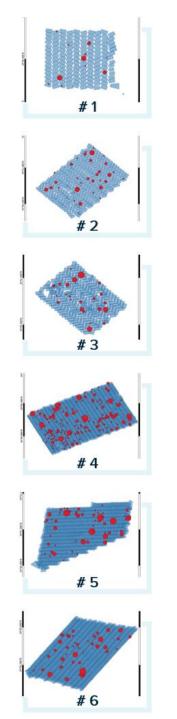
IMDOS FOR A CLEAN OCEAN

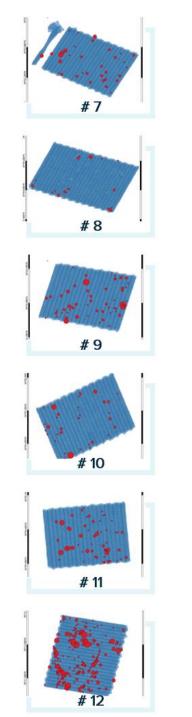
## UNMANNED AERIAL VEHICLES

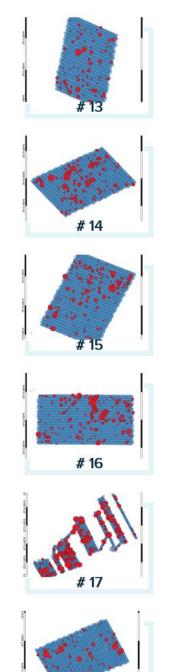
Advances in UAV technology allows for offshore deployments for the capture of aerial imagery.

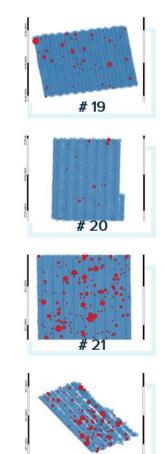
Amphibious fixed wing UAVs can produce several square kilometers of high-resolution imagery during one flight.

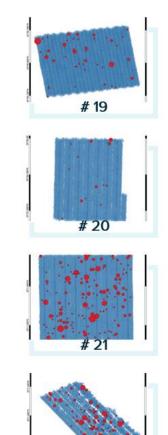
11.62 # km^-2











# # 22

#### IMDOS FOR A CLEAN OCEAN

### **UNMANNED AERIAL VEHICLES**

Advances in UAV technology allows for offshore deployments for the capture of aerial imagery.

Amphibious fixed wing UAVs can produce several square kilometers of high-resolution imagery during one flight.

One recent mission overview:

Total flight 22 flights 26.85 hours Total airtime 21,185 Photos taken 95 km<sup>2</sup> Total area scanned # debris detected (>50 cm) 2,419 3 #km<sup>2</sup> Min. concentration Max. concentration 78 #/km<sup>2</sup>

### DETECTION IN RIVERS

The same principle can be applied in different environments such as rivers with fixed cameras installed on bridges.



### Earth and Space Science

RESEARCH ARTICLE 10.1029/2019EA000960

#### Key Points:

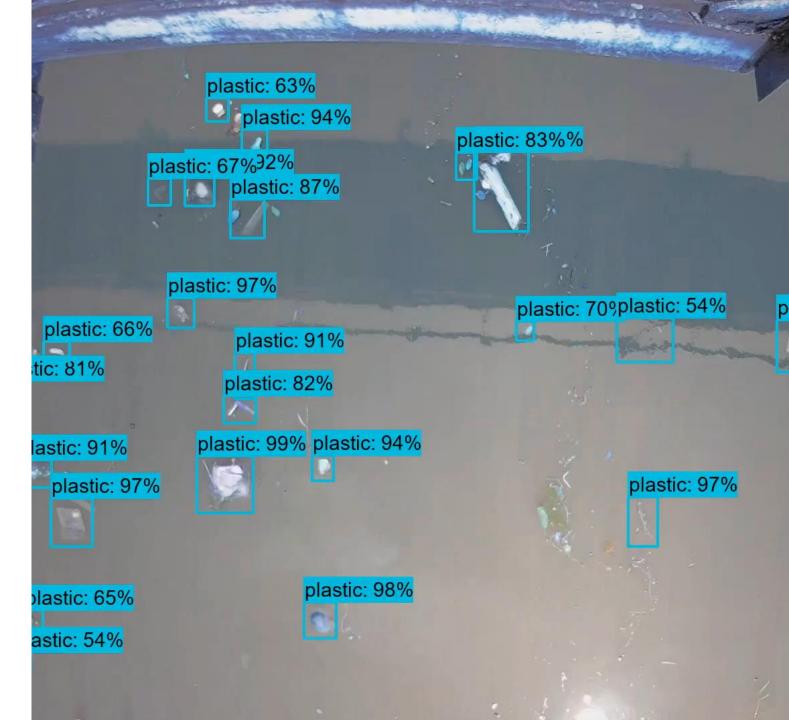
- The proposed automated monitoring method locates river plastic on images reliably
- The method generalizes reasonably well to new locations and would benefit from a larger data set
- Automated method counts agree reasonably with manual methods

### Automated River Plastic Monitoring Using Deep Learning and Cameras

Colin van Lieshout<sup>1,2,3</sup> [6], Kees van Oeveren<sup>1</sup> [6], Tim van Emmerik<sup>1,4</sup> [6], and Eric Postma<sup>2,5</sup> [6]

<sup>1</sup>The Ocean Cleanup, Rotterdam, The Netherlands, <sup>2</sup>Jheronimus Academy of Data Science, 's-Hertogenbosch, The Netherlands, <sup>4</sup>Soda science, 's-Hertogenbosch, The Netherlands, <sup>4</sup>Hydrology and Quantitative Water Management Group, Wageningen University, Wageningen, The Netherlands, <sup>5</sup>Cognitive Science and AI, Tilburg University, Tilburg, The Netherlands









IMDOS FOR A CLEAN OCEAN

### **DETECTION IN RIVERS**

#### Off-the-shelf solar powered solution:

Camera and level gauge telemetry module. Preferred settings:

Image burst: Sampling interval: Communication interval:

Image dimensions:

Operational time:

Frame rate:

3 images 15 minutes

15 minutes 4056x3130 pixels

automatically

4 FPS





## VESSEL MOUNTED CAMERAS

Cameras can be deployed on vessels to detect marine debris. The challenges are different from rivers (e.g. camera orientation)





Communication

Quantifying Floating Plastic Debris at Sea Using Vessel-Based Optical Data and Artificial Intelligence

Robin de Vries 1,\*, Matthias Egger 1,20, Thomas Mani 1 and Laurent Lebreton 1,3





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Cameras can be deployed on vessels to detect marine debris. The challenges are different from rivers (e.g. camera orientation)

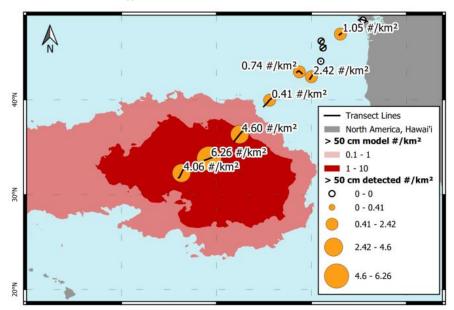


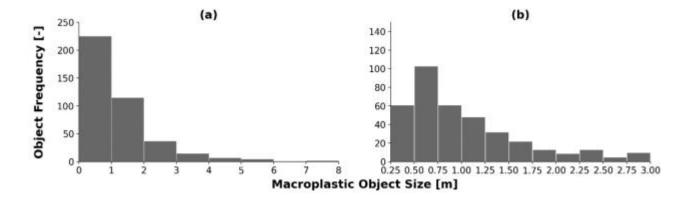


Communication

#### Quantifying Floating Plastic Debris at Sea Using Vessel-Based Optical Data and Artificial Intelligence

Robin de Vries 1,\*, Matthias Egger 1,20, Thomas Mani 1 and Laurent Lebreton 1,3



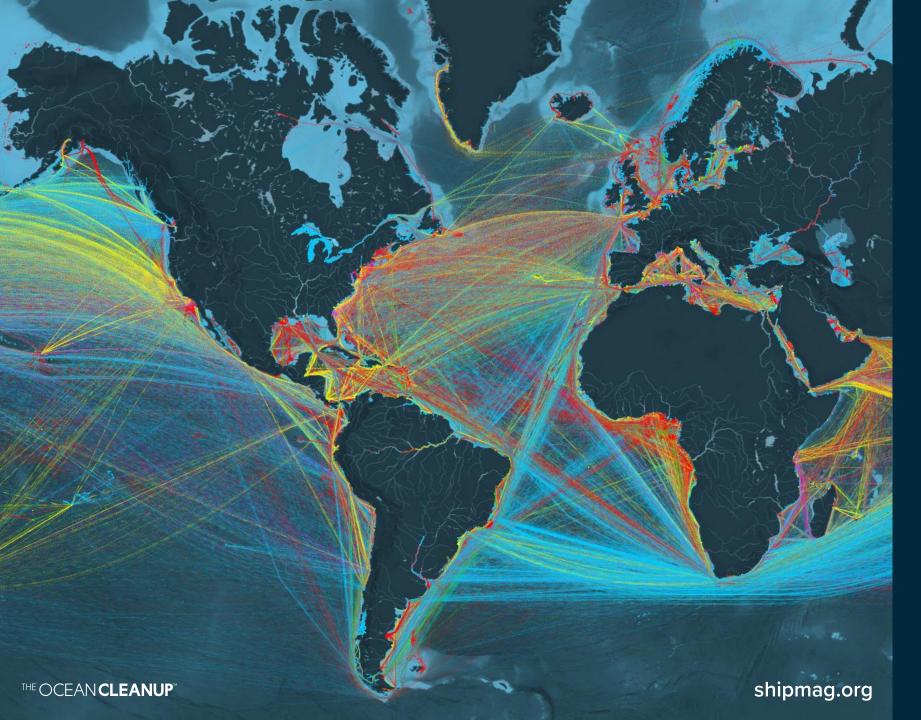








THE OCEAN **CLEANUP** 



IMDOS FOR A CLEAN OCEAN

## AUTOMATING & SCALING

Automated Debris Identification System (ADIS)





### **MERCI**